Lecture 9: High electron mobility transistor (HEMT)

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Many possible variations

- "Quantum well" is also popular.
- Highly doped material under ohmics for low contact resistance
- InP based materials
- GaN based materials
- (pHEMT: strained materials)





Triangle vs. square well:





(Draw both bound states on board.In particular discuss figure 5.21 from Liu.)Also discuss shallow vs. wide wells on board.(Typically 100 angstroms works.)

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Problem

- Presence of electrons changes shape of potential well.
- We need a way to account for this.
- Will do NOW.
- Why? We want to know how many electrons there are!
- Later, we want to know how gate voltage changes that.

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Poisson equation

Actually first of Maxwell's four equations:

$$\vec{\nabla} \cdot \vec{E} = -\frac{\rho}{\varepsilon}$$

In the x-direction only:



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Trianglular wells

 $E_1 \approx 4 \cdot 10^{-5} (\varepsilon_{i,2})^{2/3} (V/cm)$



 $\left(E_{f}-E_{1}\right)=\frac{\hbar\pi}{m_{s}}n_{s}$ m $\mathcal{E}_{i,2} = \frac{q}{\mathcal{E}_p} n_s$ $E_1 \approx 4 \cdot 10^{-5} \left(\frac{q}{\mathcal{E}_p} n_s\right)^{2/3} (V/cm)$

Discuss intuitively: adding electrons changes slope which changes Fermi energy.

That gives one relationship between E_f and n_s .

To solve for both of them, you need anothe relationship: HW 5.8

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From HW 5.8

You will find:

 $n_s \propto \sqrt{\Delta E_c} \sqrt{N_d}$

Want to engineer material so that ΔE_c large. For GaAs, there is a limit.

For $In_xGa_{1-x}As/In_xAl_{1-x}As$, use strained layers to get larger ΔE_c (discuss).

(InP has higher mobility, peak velocity than GaAs.)

Called pseudomorphic HEMT: pHEMT.

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$n_s vs E_f$

After all that mumbo-jumbo, we know it is complicated. We approximate it many times as:

$E_f(n_s) = E_{f,0} + a \cdot n_s$











$$\begin{aligned} \text{Current}\\ \text{J is 2d, n}_{s} \text{ is 2d. (Discuss).} & J = e \cdot \mu \cdot n_{s} \cdot E\\ I_{D} = J \cdot (width) = e \cdot \mu \cdot n(x) \cdot E(x) \cdot W\\ I_{D} = \mu \cdot C_{ox} (V_{GS} - V_{T} - V_{CS}(x)) \cdot E(x) \cdot W\\ = \mu \cdot C_{ox} (V_{GS} - V_{T} - V_{CS}(x)) \cdot \frac{\partial V_{CS}(x)}{\partial x} \cdot W\end{aligned}$$

$$\begin{aligned} \text{Integrating:} \\ I_D &= \mu \cdot C_{ox} \left(V_{GS} - V_T - V_{CS}(x) \right) \cdot \frac{\partial V_{CS}(x)}{\partial x} \cdot W \\ \int_0^L I_D dx &= \int_0^L \mu \cdot C_{ox} \left(V_{GS} - V_T - V_{CS}(x) \right) \cdot \frac{\partial V_{CS}(x)}{\partial x} \cdot W dx \\ &= \int_{V_{CS}(0)}^{V_{CS}(L)} \mu \cdot C_{ox} \left(V_{GS} - V_T - V_{CS}(x) \right) \cdot \partial V_{CS}(x) \cdot W = doable \\ \hline I_D &= \frac{W \cdot \mu \cdot C_{ox}}{L} \left[(V_{GS} - V_T) V_{DS} - \frac{V_{DS}^2}{2} \right] \end{aligned}$$



Channel potential: $J = e \cdot \mu \cdot n_s \cdot E$ $I_D = J \cdot (width) = e \cdot \mu \cdot n(x) \cdot E(x) \cdot W$

Since we are in 2d, no position dependent thickness b(x). Life is easier. It can be shown that:

$$V_{CS}(x) = \left(V_{GS} - V_T\right) \left[1 - \sqrt{1 - \frac{x}{L}\left(1 - \alpha^2\right)}\right]$$
$$\alpha = \begin{cases} 1 - V_{DS} / V_{DS,sat} & \text{for } V_{DS} < V_{DS,sat} \\ 0 & \text{for } V_{DS} > V_{DS,sat} \end{cases}$$

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Velocity saturation

- Just like MESFETs
- Important in short channel HEMTs
- Need to model channel as to regions: saturated and unsaturated
- Qualitative IVs are similar